

PRESSURE DROP FOR FLOW OF POWER LAW FLUIDS INSIDE ELLIPTICAL DUCTS

Cássio Roberto Macedo Maia

Faculdade de Engenharia de Ilha Solteira / Unesp
cassio@dem.feis.unesp.br

João Batista Aparecido

Faculdade de Engenharia de Ilha Solteira / Unesp
jbbaparec@dem.feis.unesp.br

Luiz Fernando Milanez

Faculdade de Engenharia Mecânica / Unicamp
milanez@fem.unicamp.br

Abstract. *The hydrodynamic analysis for non-Newtonian flow inside straight ducts with elliptical cross-section was performed in this work for low Reynolds number. Power law fluids were considered since the most known non-Newtonian ones falls within this model. Simplified hypotheses for the fluid flow were established by adopting an adequate coordinate system, allowing to obtain a close form solution for the momentum equation. The flow field and physical parameter of interest such as average velocity and Fanning friction factor were then determined and presented as function of the behavior index and elliptical tube aspect ratio.*

Keywords. *power law, non-Newtonian, pressure drop, elliptical duct, fluid flow, friction factor*

1. Introduction

Situations that involve processing non-Newtonian fluids characterize research field that has many applications mainly in chemical, pharmaceutical, food processing and petrochemical industries. Thus, rheological research that deals with the relation between shear stress and gradient of the velocity field are of fundamental importance for fluid characterization and its flow behavior. However, to obtain the solution for momentum and energy equations it is necessary to get several physical parameters of interest including those ones related to the design of thermo-hydraulics equipment processing fluid of such nature. In this way, the research concerned to the internal flow of non-Newtonian fluids has many technological applications. Along last decades, several efforts have been developed in this research field, among several we can cite Hartnett and Kostic (1989), and the works of Richardson (1979), Cho and Hartnett (1982), Cotta and Özisik (1986), Pinho and Whitelaw (1990), Billingham and Ferguson (1993), Quaresma and Macêdo (1998). It is worth noticing that the most of that work deal with the flow between parallel plates, or ducts with circular or square cross-section. Few works are dedicated to study the flow inside ducts with more complex cross-section, among some we cite the works of Etemad, Mujundur and Nassef (1996), Wachs, Clermont and Normandin (1999), and Chaves *et al.* (2001). Thus, giving continuity to this research field, this work deals with the hydrodynamic analysis involved in the flow at low Reynolds number of power law fluids inside straight ducts with elliptical cross-section. Due to flow characteristics, mentioned above, it is hypothesized that secondary flow is negligible, Tanner (2000), and that using an adequate non-orthogonal coordinate system it was possible to impose simplifying conditions in the whole flow as well to obtain a closed form solution for the velocity field. Parameters such as average velocity and Fanning friction factor were obtained as a function of the behavior index the cross-section aspect ratio.

2 Analysis

Non-Newtonian power law fluids present the following relation between the shear stress and the deformation rate:

$$\tau = K \left[\frac{dw(x,y)}{d\eta} \right]^n, \quad (1)$$

where n is the behavior index of the flow, K is the consistency index and η is an auxiliary coordinate axis orthogonal to the flow plane. That plane is a surface generated by the equation $w(x,y) = \text{constant}$. Equation (1) can be written as follows:

$$\tau = K \left| \frac{dw}{d\eta} \right|^{n-1} \left[\frac{dw}{d\eta} \right] = \mu_a \frac{dw}{d\eta}, \quad (2a)$$

$$\mu_a = \kappa \left| \frac{dw}{d\eta} \right|^{n-1}, \quad (2b)$$

where μ_a is called apparent viscosity. For pseudoplastic, $n < 1$, the apparent viscosity decreases with the increase of the shear stress. For dilatant fluids, $n > 1$, apparent viscosity increases as the shear stress increases.

To determine the velocity profile for the power law fluid flow inside straight ducts with elliptical cross-section it is assumed that the flow is laminar and hydrodynamically developed. To establish the correspondent momentum equation consider the following coordinate system:

$$x = v \cos(u), \quad (3a)$$

$$y = \rho_{asp} v \sin(u), \quad (3b)$$

$$\rho_{asp} = \beta / \alpha, \quad \{ \beta < \alpha \} \quad (3c)$$

where the ratio between the elliptical semi-axis, β / α , defines the aspect ratio, ρ_{asp} of the elliptical duct cross-section. When the aspect ratio $\rho_{asp} = 1$, the coordinate system transformation given by Equation (3a-c) generates the cylindrical coordinate system. In the general case, when the aspect ratio $\rho_{asp} < 1$, the coordinate system (u, v) is not orthogonal, and the curves generated for $v = \text{constant}$ looks like similar ellipsis, concentric at $(0,0)$ as shown in Figure 1.

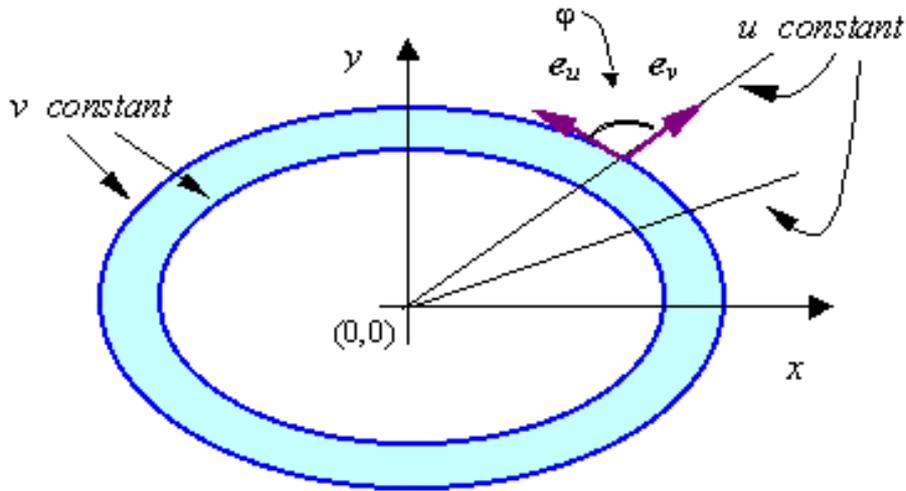


Figure 1. Non-orthogonal coordinate system (u, v) .

Metric coefficients $h_u(u, v)$ and $h_v(u, v)$, and the unitary base vectors e_u and e_v for the new coordinate system are given by

$$\frac{d\mathbf{r}}{du} = h_u(u, v) e_u = -v \sin(u) \hat{\mathbf{i}} + \rho_{asp} v \cos(u) \hat{\mathbf{j}}, \quad (4a)$$

$$\frac{d\mathbf{r}}{dv} = h_v(u, v) e_v = \cos(u) \hat{\mathbf{i}} + \rho_{asp} \sin(u) \hat{\mathbf{j}}, \quad (4b)$$

$$h_u(u, v) = \left| \frac{d\mathbf{r}}{du} \right| = v \sqrt{\sin^2(u) + \rho_{asp}^2 \cos^2(u)} , \quad (5a)$$

$$h_v(u, v) = \left| \frac{d\mathbf{r}}{dv} \right| = \sqrt{\cos^2(u) + \rho_{asp}^2 \sin^2(u)} , \quad (5b)$$

$$\mathbf{e}_u = v [-\sin(u)\hat{\mathbf{i}} + \rho_{asp}\cos(u)\hat{\mathbf{j}}] / h_u(u, v) , \quad (6a)$$

$$\mathbf{e}_v = [\cos(u)\hat{\mathbf{i}} + \rho_{asp}\sin(u)\hat{\mathbf{j}}] / h_v(u, v) . \quad (6b)$$

Due to the geometrical characteristics of ellipsis cross-section it is assumed that fluid velocity changes with the u axis is negligible (Ahmeda, Normandin and Clermont, 1995). Therefore, $w = w(v)$. Defining an axis η orthogonal to the curve $w = w(v)$ and pointing towards the wall of the duct, then the constitutive equation for the shear stress, Equation (1), can be written as

$$\boldsymbol{\tau} = K \left[\frac{dw(v)}{d\eta} \right]^n . \quad (7)$$

As the coordinate system (u, v) is non-orthogonal, the component orthogonal to the fluid flow plane does not coincide with the unitary base vector \mathbf{e}_v . Thus, a differential $d\eta$ must be determined not forgetting the non-orthogonality of the coordinate system. In order to do so, a generic vector element $d\mathbf{r}$ is projected into a unitary base vector \mathbf{e}_η orthogonal do fluid flow plane. By doing so, we have

$$d\eta = d\mathbf{r} \cdot \mathbf{e}_\eta = [h_u(u, v) du \mathbf{e}_u + h_v(u, v) dv \mathbf{e}_v] \cdot \mathbf{e}_\eta , \quad (8a)$$

$$\mathbf{e}_\eta = \mathbf{e}_u \times \frac{(\mathbf{e}_v \times \mathbf{e}_u)}{\sin(\varphi)} , \quad (8b)$$

$$\sin(\varphi) = |\mathbf{e}_v \times \mathbf{e}_u| = \frac{\rho_{asp} v}{h_u(u, v) h_v(u, v)} , \quad (8c)$$

where φ is the angle between the unitary base vectors \mathbf{e}_u and \mathbf{e}_v . As $\mathbf{e}_u \perp \mathbf{e}_\eta$, the differential $d\eta$ is then determined and given by

$$d\eta = h_v(u, v) dv (\mathbf{e}_v \cdot \mathbf{e}_\eta) , \quad (9a)$$

$$(\mathbf{e}_v \cdot \mathbf{e}_\eta) = |\mathbf{e}_v \times \mathbf{e}_u| = \sin(\varphi) , \quad (9b)$$

$$d\eta = h_v(u, v) \sin(\varphi) dv = \rho_{asp} v dv / h_u(u, v) . \quad (9c)$$

Therefore, an equation for the shear stress in the new coordinate system is written as

$$\boldsymbol{\tau} = K \left[-\frac{h_u}{\rho_{asp} v} \frac{dw(v)}{dv} \right]^n . \quad (10)$$

Pressure forces and shear stress forces acting on an elliptical ring element (shown in Figure 2) with thickness $d\eta$ and length dz , can be formulated as follow

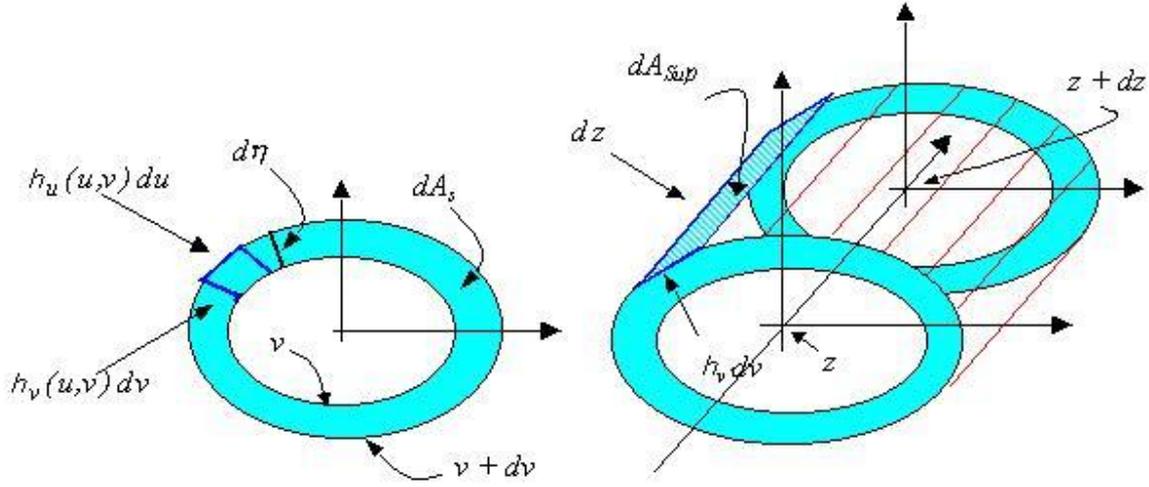


Figure 2. – Visualization of elliptical and axial differential elements having areas dA_s and dA_{sup} in order to determine pressure and shear stress forces.

$$dF_P(z) = P(z) dA_s, \quad dA_s = \int_0^{2\pi} [h_u(u,v) h_v(u,v) \sin(\varphi) du] dv, \quad (11a)$$

$$dF_P(z+dz) = P(z+dz) dA_s = [P(z) + \frac{dP(z)}{dz} dz] dA_s, \quad (11b)$$

$$dF_{visc}(v) = \int_{A_{sup}} \tau(u,v) dA_{sup} = \int_0^{2\pi} [\tau(u,v) h_u(u,v) du] dz \quad (12a)$$

$$dF_{visc}(v+dv) = dF_{visc}(v) + \frac{d}{dv} \int_0^{2\pi} [\tau(u,v) h_u(u,v) du] dz dv. \quad (12b)$$

Substituting the expression for $\sin(\varphi)$, into the metric coefficients h_u and h_v , and into the shear stress equation τ , the net result for the pressure forces acting on elliptical ring element is

$$d[F_P(z+dz) - F_P(z)] = - \int_0^{2\pi} \left[\frac{dP}{dz} \frac{v \rho_{asp}}{h_u h_v} h_u h_v du \right] dv dz, \quad (13a)$$

$$d[F_P(z+dz) - F_P(z)] = 2\pi \rho_{asp} v \left[-\frac{dP}{dz} \right] dz, \quad (13b)$$

and for the shear stress forces,

$$d[F_{visc}(v+dv) - F_{visc}(v)] = \frac{d}{dv} \int_0^{2\pi} \left\{ \kappa \left[-\frac{h_u}{\rho_{asp} v} \frac{dw}{dv} \right]^n h_u du \right\} dv dz, \quad (14a)$$

$$d[F_{visc}(v + dv) - F_{visc}(v)] = \kappa \rho_{asp} \left[-\frac{dw}{dv} \right]^n I(n, \rho) dv dz, \quad (14b)$$

with

$$I(n, \rho_{asp}) = \int_0^{2\pi} [1 + q \sin^2(u)]^{\frac{n+1}{2}} du, \quad q = \frac{1 - \rho_{asp}^2}{\rho_{asp}^2} > 0. \quad (15)$$

From the equilibrium between the viscous and pressure forces, we have

$$2\pi \frac{dP}{dz} \rho_{asp} v = \kappa \rho \left[-\frac{dw}{dv} \right]^n I(n, \rho_{asp}). \quad (16)$$

By doing some changes in the above equation and also considering that the maximum velocity occurs at the centerline of the flow, we obtain the following relation for the flow field inside the duct elliptical cross-section

$$w(v) = w_{max} \left\{ 1 - \left[\left(\frac{v}{\alpha} \right)^2 \right]^{\frac{n+1}{2n}} \right\} = w_{max} \left\{ 1 - \left[\left(\frac{x^2}{\alpha^2} + \frac{y^2}{\beta^2} \right)^2 \right]^{\frac{n+1}{2n}} \right\} \quad (17a)$$

$$w_{max} = \left[\frac{n}{n+1} \right] \left[-\frac{dP}{dz} \frac{2\pi}{\kappa I(n, \rho_{asp})} \right]^{\frac{1}{n}} \alpha^{\frac{n+1}{n}} \quad (17b)$$

The average velocity is obtained as follows

$$w_m = \frac{1}{A_s} \int_{A_s} w(x, y) dA = \left[\frac{n+1}{3n+1} \right] w_{max}. \quad (18)$$

Thus, the velocity distribution can also be written in terms of the average velocity, yielding

$$w(x, y) = \left[\frac{3n+1}{n+1} \right] \left\{ 1 - \left[\frac{x^2}{\alpha^2} + \frac{y^2}{\beta^2} \right]^{\frac{n+1}{2n}} \right\} w_m. \quad (19)$$

3. Friction coefficient

Fanning friction coefficient is defined as

$$f = \frac{\tau_{p,m}}{\rho w_m / 2}. \quad (20)$$

The average shear stress at duct wall $\tau_{p,m}$, appearing in the definition of the Fanning friction coefficient, equation above, is defined and determined by

$$\tau_{p,m} = \frac{dF_{visc}|_{v=\alpha}}{P dz} = \frac{\left(\int_0^{2\pi} \kappa \left[-\frac{h_u}{\rho_{asp} v} \frac{dw}{dv} \right]^n \Big|_{v=\alpha} h_u du \right) dz}{P dz}. \quad (21)$$

From the results obtained for the metric coefficient h_u and from the velocity profile $w(v)$, Equations (5a and 17a), the Fanning friction factor, f , is then obtained,

$$f = \frac{2K}{\rho w_m^{2-n}} \left[\frac{3n+1}{n} \right]^n \frac{\rho_{asp} I(n, \rho_{asp})}{\alpha^{n-1} P}, \quad (22)$$

with $I(n, \rho_{asp})$ given by Equation (15).

The above equation is written again, now introducing the Reynolds number, Re , and the hydraulic diameter, D_h ,

$$f Re = 16 \frac{I(n, \rho_{asp})}{2\pi} \left[\frac{D_h}{2\alpha} \right]^{n+1}, \quad (23)$$

where the corresponding hydraulic diameter, D_h , and the Generalized Reynolds number (Skelland, 1967), Re , is given by

$$D_h = \frac{4 \times \text{Cross-section area}}{\text{Cross-section perimeter}} \quad (24a)$$

$$Re = \frac{\rho w_m^{2-n} D_h^n}{8^{n-1} K \left[\frac{3n+1}{4n} \right]^n}. \quad (24b)$$

When $\rho_{asp} = 1$, the factor $I(n, \rho_{asp}) = 2\pi$. Therefore, for circular ducts we have $f Re = 16$, independently of the behavior index, n .

4. Results and remarks

To determine the Fanning friction coefficient, the integral for the factor $I(n, \rho_{asp})$, given by Equation (15), was calculated by using Gauss quadrature method. The product $f Re$ was determined through Equation (23) for various ellipsis aspect ratio ($\rho_{asp} = 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9$ and 1) and for some behavior index ($n = 0.1, 0.2, 0.3, 0.5, 0.7, 1, 2, 3, 4$ and 5). Results obtained for the product $f Re$ are presented numerically in Table (1) and are visualized graphically on Fig. (3). It can be figure out that the friction factor for pseudoplastic fluids ($n < 1$) changes little with the aspect ratio. For dilatant fluids ($n > 1$) the friction factor exhibits a strong dependency to the ellipsis aspect ratio when it tends toward zero ($\rho_{asp} \rightarrow 0$). In such cases, the apparent viscosity of dilatant fluids increases significantly, due to the higher fluid velocity gradients near the wall.

In order to validate the results, values in the literature were found for the particular case of unitary the behavior index, $n = 1$ (Shah and London, 1978) and it can be observed in Table 2 that there is an excellent agreement with the results presented here. It is interesting to notice that for the particular case of unitary aspect ratio, $\rho_{asp} = 1$, the Equation (19) gives the same solution for the flow in circular tubes, Skelland (1967)

$$w(x, y) = \left[\frac{3n+1}{n+1} \right] \left[1 - \left(\frac{r}{R} \right)^{\frac{n+1}{n}} \right] w_m, \quad (25)$$

where R is the circular radius. In Figures 4 to 6 present graphically the velocity profiles for fluid flow with behavior index, $n = 0.1, n = 1$ and $n = 5$, respectively, inside ducts with aspect ratio, $\rho_{asp} = 0.5$.

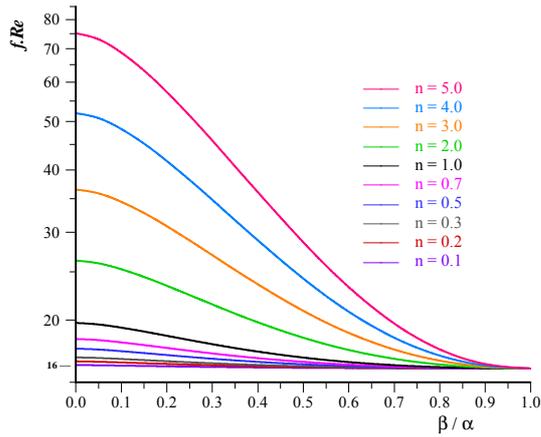


Figure 3 – Fanning friction factor fRe as function of the aspect ratio, ρ_{asp} , and behavior index, n .

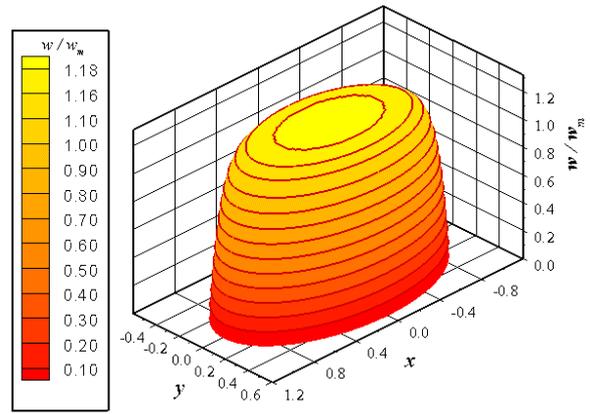


Figure 4 – Velocity profile for flow of pseudoplastic fluid with behavior index, $n = 0.1$, inside a duct with aspect ratio, $\rho_{asp} = 0.5$.

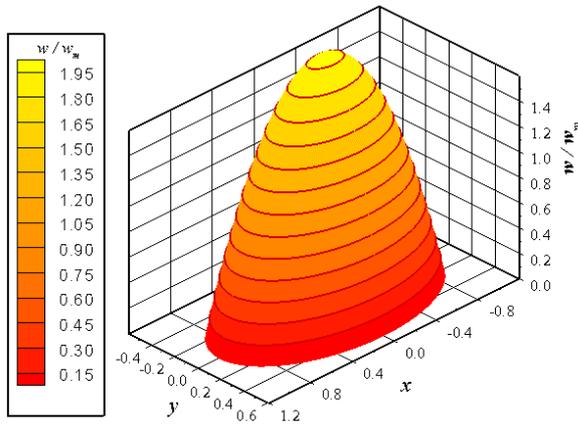


Figure 5 - Velocity profile for flow of Newtonian fluid with behavior index, $n = 1$, inside a duct with aspect ratio, $\rho_{asp} = 0.5$.

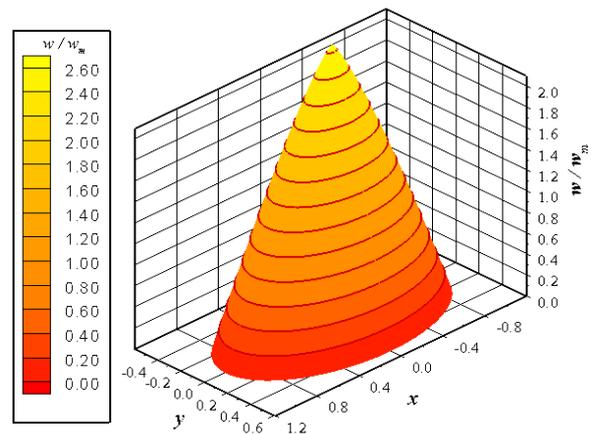


Figure 6 - Velocity profile for flow of dilatant fluid with behavior index, $n = 5$, inside a duct with aspect ratio, $\rho_{asp} = 0.5$.

5. Final remarks

A closed form solution for the flow of non-Newtonian power law fluids inside straight ducts with elliptical cross-section was obtained in this work. The hydrodynamic parameters for the developed flow were determined. A model was established in which the planes of constant velocities in the flow approximate to the boundary of a family of similar ellipsis concentric to the duct. In this way, a new non-orthogonal coordinate system (u, v) was proposed, that is able to generate elliptical curves when the variable v is fixed. In this new system of coordinates the fluid flow velocity can be expressed as a function of only one independent variable, $V = V(v)$, simplifying substantially the formulae of the problem.

Through the viscous and pressure forces equilibrium was determined the velocity flowfield and hydrodynamic parameters such as the average flow velocity and the Fanning friction factor were determined through the viscous and pressure forces equilibrium, allowing the analysis of the flow of pseudoplastic and dilatant non-Newtonian fluids as a function of the behavior index and the aspect ratio.

6. Acknowledgement

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Table 1 - Parameter fRe as function of aspect ratio, ρ_{asp} , and behavior index, n .

n ρ_{asp}	0.1	0.2	0.3	0.5	0.7	1.0	2.0	3.0	5.0
0.999	16.0000	16.0000	16.0000	16.0000	16.0000	16.0000	16.0000	16.0000	16.0000
0.90	16.0012	16.0027	16.0043	16.0083	16.0132	16.0221	16.0663	16.1327	16.3320
0.80	16.0054	16.0118	16.0191	16.0368	16.0583	16.0979	16.2933	16.5867	17.4734
0.75	16.0089	16.0194	16.0315	16.0605	16.0959	16.1610	16.4817	16.9635	18.4268
0.70	16.0135	16.0294	16.0478	16.0918	16.1454	16.2439	16.7287	17.4575	19.6851
2 / 3	16.0173	16.0376	16.0611	16.1173	16.1857	16.3113	16.9293	17.8586	20.7138
0.60	16.0267	16.0582	16.0943	16.1808	16.2861	16.4789	17.4258	18.8515	23.2868
0.50	16.0464	16.1009	16.1634	16.3125	16.4932	16.8233	18.4368	20.8730	28.6427
0.40	16.0741	16.1607	16.2598	16.4949	16.7785	17.2941	19.7981	23.5938	36.0969
1 / 3	16.0976	16.2114	16.3411	16.6475	17.0155	17.6815	20.8991	25.7924	42.3226
0.30	16.1110	16.2401	16.3869	16.7321	17.1477	17.8960	21.5005	26.9925	45.7961
0.25	16.1330	16.2872	16.4620	16.8721	17.3611	18.2400	22.4514	28.8879	51.3872
0.20	16.1573	16.3386	16.5435	17.0216	17.5885	18.6024	23.4337	30.8424	57.2851
1 / 6	16.1745	16.3748	16.6003	17.1246	17.7439	18.8473	24.0845	32.1344	61.2545
1 / 7	16.1871	16.4011	16.6414	17.1985	17.8544	19.0199	24.5357	33.0282	64.0319
1 / 8	16.1967	16.4209	16.6722	17.2532	17.9358	19.1458	24.8608	33.6712	66.0450
1 / 9	16.2043	16.4362	16.6958	17.2950	17.9974	19.2407	25.1029	34.1491	67.5489
0.10	16.2103	16.4484	16.7144	17.3276	18.0453	19.3139	25.2881	34.5140	68.7018
1 / 16	16.2307	16.4877	16.7736	17.4291	18.1923	19.5358	25.8381	35.5944	72.1326
0.05	16.2374	16.4997	16.7913	17.4585	18.2342	19.5977	25.9880	35.8873	73.0664
0.001	16.2570	16.5319	16.8362	17.5294	18.3321	19.7391	26.3184	36.5279	75.1068

Table 2 – Fanning friction factor comparison for Newtonian fluid, fRe .

ρ_{asp}	0.999	0.90	0.80	0.75	0.70	2 / 3	0.60	0.50	0.40
fRe	16.0000	16.0221	16.0979	16.1610	16.2439	16.3113	16.4789	16.8233	17.2941
$fRe^{(*)}$	16.000	16.022	16.098	16.161	16.244	16.311	16.479	16.823	17.294

Table 2 (continuation).

ρ_{asp}	1 / 3	0.30	0.25	0.20	1 / 6	1 / 8	0.10	0.05	0.001
fRe	17.6815	17.8960	18.2400	18.6024	18.8473	19.1458	19.3139	19.5977	19.7391
$fRe^{(*)}$	17.681	17.896	18.240	18.602	18.847	19.146	19.314	19.598	19.739

(*) Results from Shah and London (1978).

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